Assignments for Meeting on Jan. 26, 2021 (1/2)

Implement the computation of the shortest path for the Dubins’ vehicle, given an initial configuration and another desired goal configuration. Validate your implementation against another available library (several available online both for Matlab and Python).

**Next meeting:** Tuesday January 26, 2021, at 15:15 in Zoom.

**Lecture responsibility:** Faseeh Ahmad.